

## Unit 1 Textile Technology Lecture 1.4 Advances in braiding production

D 2.1 Training toolkit and e-book

May 2021 – Luminita Ciobanu (TUIASI)



WINTEX project (Weaving innovation among academia and industry in the Tunisian textile sector; project reference number 610373-EPP-1-2019-1-ES-EPPKA2-CBHE-JP) is co-funded by the Erasmus+ programme of the European Union.

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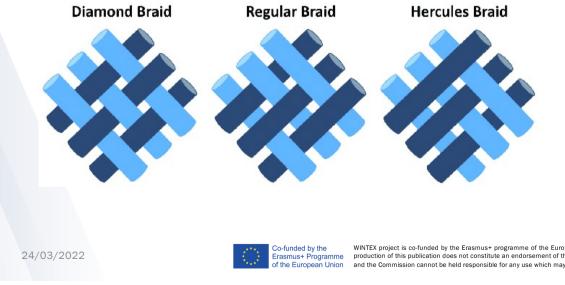


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### **General characterization of braiding**

**Braiding** is a textile process based on the intertwining of at least one set of yarns in bias directions. The intertwining positions the two sets of yarns at an angle between 10° and 80°.



The ratio with which the yarns are intertwined defines the structure of the braided fabrics: 1x1 (diamond), 2x2 (regular) and 3x3 (Hercules).

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#### Structural braid notations

The "English" system consists of a few specified names for the popular structures – regular, basked and diamond. One more clear system from the engineering point of view describes structures in a form following "one over and under one," "one over and under two," etc.

The "German" system is based on two numbers – the first describing the intersection type and the second the number of yarns per group. The system defines the floating length (Flechtigkeit) which describe how many yarns build the braid.

The pattern notation rule is:

Over X groups: Under X groups – As a group of Y yarns



3:3-1



1:1-1

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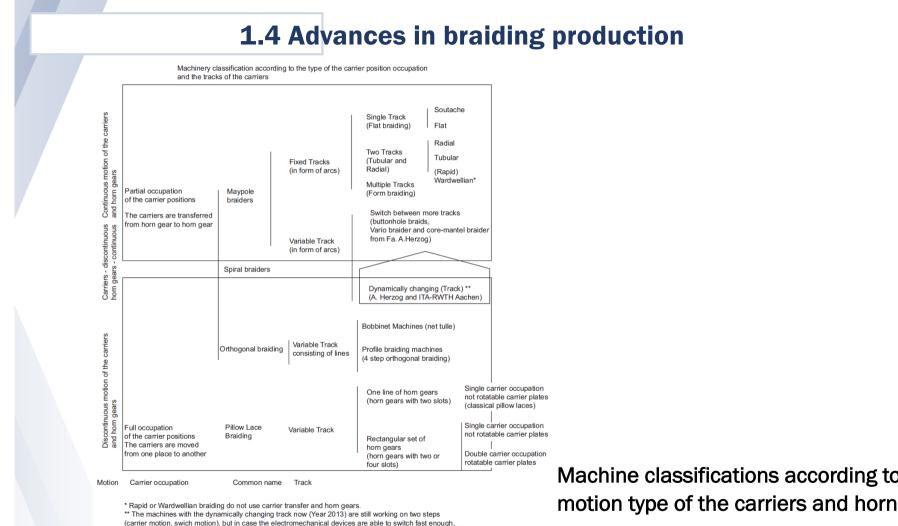


#### Applications of braided structures

- clothing (outwear and lingerie); shoelaces;
- candle wicks;
- sleeves, cords, harnesses and ropes used for fishing and seafaring, offshore drilling, aeronautic industry and automotive;
- protection for electric cables;
- sport and leisure;
- composite reinforcement;
- medical textiles scaffolds (tissue engineering), hard implants and non-implantable applications, such as elastic/nonelastic bandages, compression garments or orthopaedic devices.







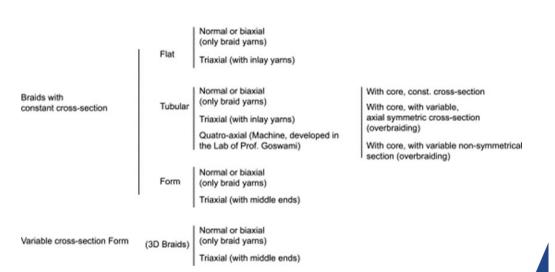
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these machines will belong to the type of machines with continuous carrier and horn gear motion.

Machine classifications according to the motion type of the carriers and horn gears

### 1. 2D braiding

2D braiding is the most common braiding process, in industrial and commercial terms. It includes different braiding principles, referring mainly to the way the horn gears are placed and carriers moved and the way the yarns interlace: **maypole braiding**, spiral braiding, lace braiding, bobbinet braiding.

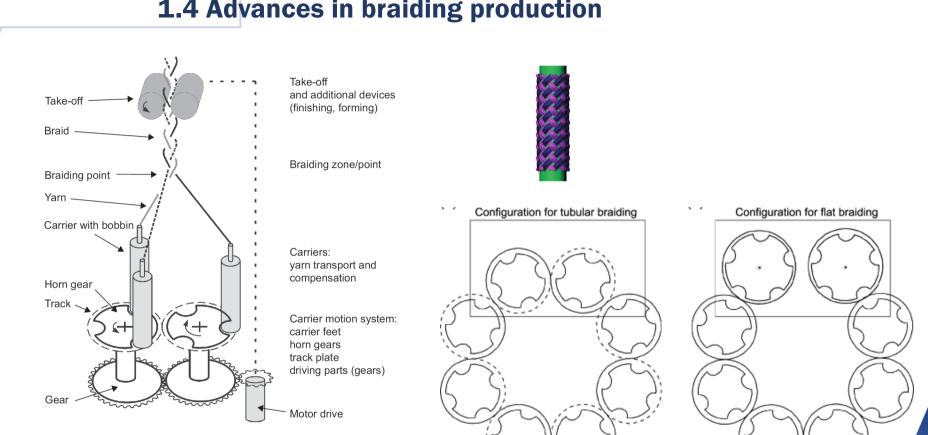


Braids from maypole machines



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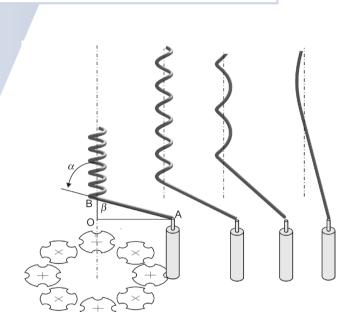
#### Basic principle of maypole braiding

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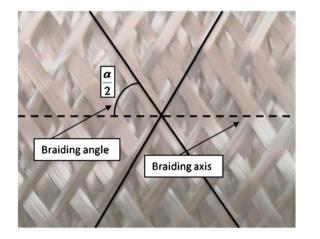


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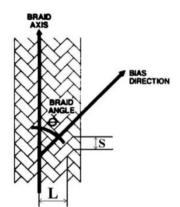




position of the natural braiding point depends on the take-off speed



position of the natural braiding point determines the braiding angle

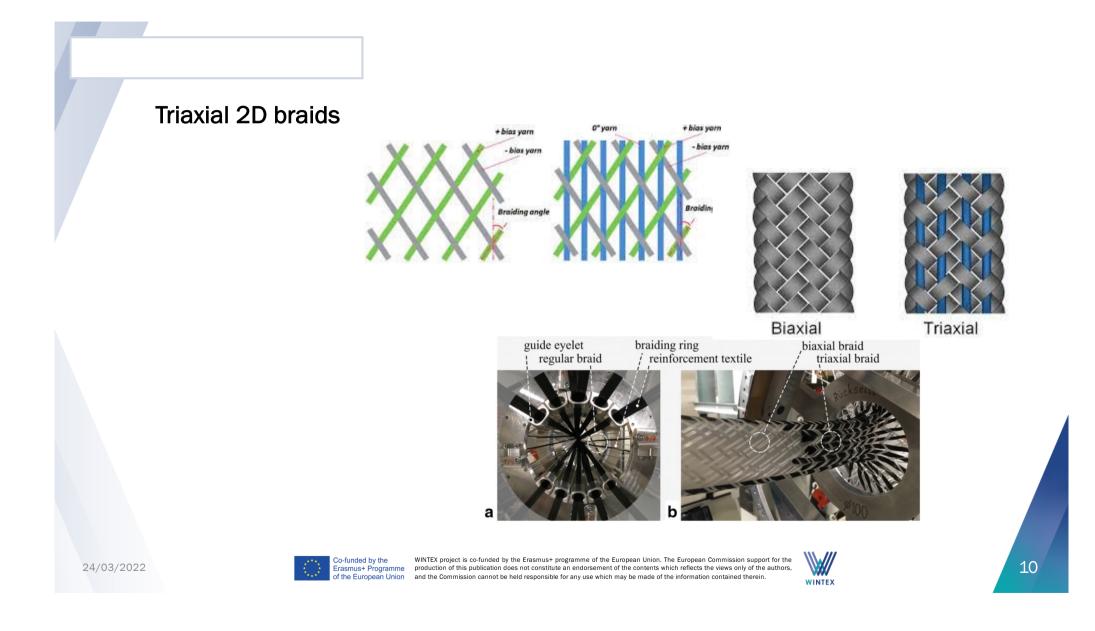


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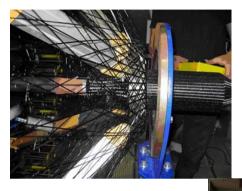


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**1.2. Overbraiding** is achieved by using a shaped mandrel, placed on the braiding axis throughout the braiding process. The braided structure covers the mandrel in several layers, resulting in a preform that is generally used for composite reinforcement.



Certain machines have the mandrel positioned by a robotic arm, that can control its angle in relation to the braiding axis.



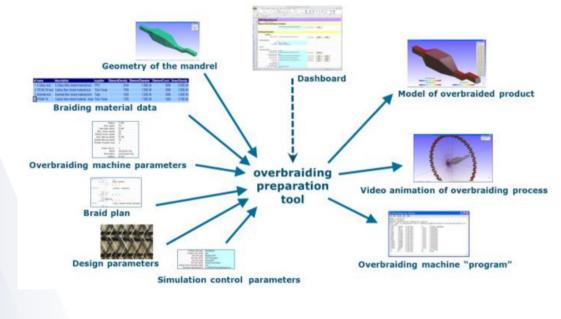


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The main problem for overbraiding is to digitalize the braiding process, creating tools that will allow the programming of the braiding machine according to the geometry of the mandrel used, so that the resulting preform will have specific characteristics and will correspond to quality standards.



National Aerospace Laboratory NLR in the Netherlands, in collaboration with Eurocarbon BV and University of Twente developed an overbraiding preproduction support tool destined to replace the labour intensive, trial-and-error prototyping process.

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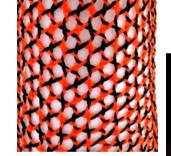
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**1.2. Lace braiding** is a process similar to maypole braiding (circular or flat) where each horn gear is controlled individually, so that its movement direction can be reversed after each cycle to create independent strands.



TEF Braids (USA) develops complex lace braids based on proprietary technologies for Jacquard lace braiding. The tension distributive fabric structures are based on several patents: XheIX, IP (US 20140377488 A1) and ALX that allow extremely diverse structural possibilities.





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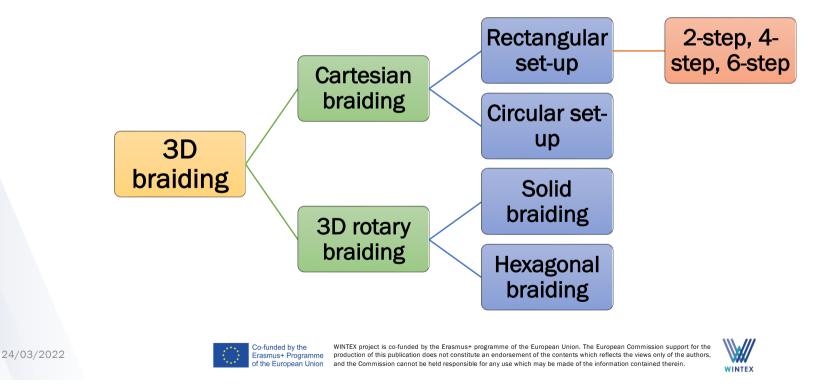
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< 2013 | TEF BRAIDS | Film

## 2.3D braiding

3D braiding is characterised by the diversity of shapes, cross-sections and their through-thickness controlled mechanical behaviour based on yarn geometry.



3D shapes can be obtain through 2D braiding, the resulting tubular braids being altered to correspond to 3D shapes

(b) Collapsed braid region Core materials Hollow area

Deforming

Schematical view of two-dimensional (2D) triaxial-braided tube before and after deformation making a sectional structural shape



(a)



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1.4	Ad	vances	in	braiding	production
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Number of yarn sets	3D Braid		3D axial braid		Multiaxis 3D braid		
	Cartesian	Polar	Cartesian	Polar	Cartesian	Polar	
l or 2	Square Rectangular Through-the-thick- ness (Out-of-plane at an angle) I × I pattern 2 × I pattern	<ul> <li>Tubular</li> <li>Through-the-thickness (Out-of-plane at an angle)</li> <li>I × I pattern 2 × I pattern 3 × I pattern 4 × I pattern</li> </ul>			Rectangular • Through-the-thick- ness (Out-of-plane at an angle)	Tubular • Through-the-thick ness (Out-of-plan at an angle)	
3	3 × I pattern 4 × I pattern		<ul> <li>Triaxial fabric</li> <li>Braid yarn in surface (In-plane)</li> <li>Rectangular</li> <li>Through-the-thick- ness (Out-of-plane at an angle)</li> <li>I × I pattern 2 × I pattern 3 × I pattern</li> </ul>	<ul> <li>Triaxial fabric</li> <li>Braid yarn in surface (In-plane)</li> <li>Tubular</li> <li>Through-the-thick- ness (Out-of-plane at an angle)</li> <li>I × I pattern 2 × I pattern 3 × I pattern</li> </ul>	Rectangular • Through-the-thick- ness (Out-of-plane at an angle)	Tubular • Through-the-thick ness (Out-of-plan at an angle)	
4			4 × I pattern	4 × I pattern	Rectangular • Through-the-thick- ness (Out-of-plane	Tubular • Through-the-thick ness (Out-of-plan	
5 or 6					at an angle) Rectangular • Through-the-thick- ness (Out-of-plane at an angle)	at an angle) Tubular • Through- the thickness (Out-o plane at an angle)	

## Classification of 3D braids



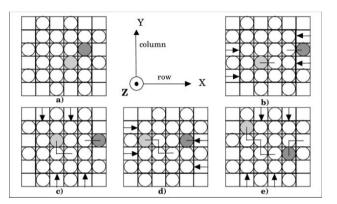
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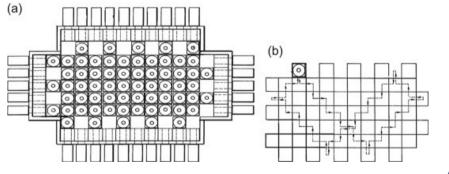
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#### 2.1. Cartesian 3D braiding

For **cartesian 3D braiding** (track-and-column braiding) carriers are moved in groups, by tracks, respectively columns. In the 4-step process tracks and then columns of carriers are successively displaced in opposite directions in four stages.



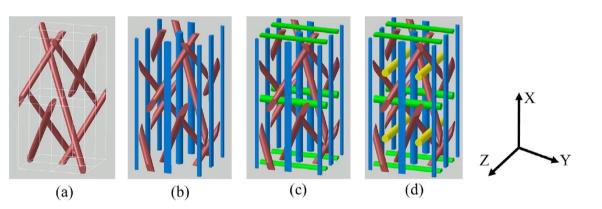


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Geometry of reinforced cartesian braided structures - a) 3D 4d (only braiders), b) 3D5d (+warp yarns), c) 3D6d (+warp and filling yarns) and d) 3D7d (+warp yarns, filling yarns and Z-axis yarns)

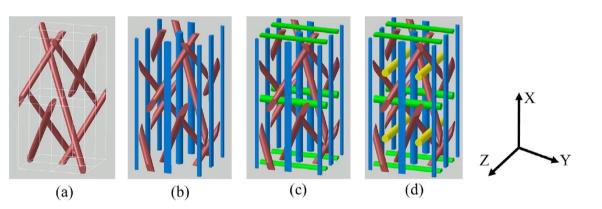
6-step braiding process was developed based on the 4-step one to increase the fabric strength on all three directions by introducing yarns parallel to the axis (warp yarns, filling yarns and Z-axis yarns).





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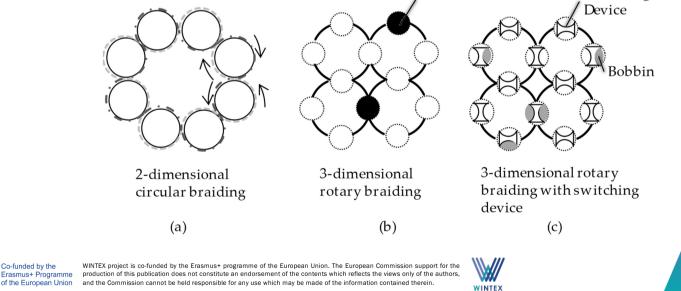


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#### 2.2. 3D rotary braiding

3D rotary braiding process is an adaptation of maypole and lace braiding with a different arrangement of horn gears (rectangular) and, most important, modified mechanism for track-switching of the carriers between horn gears so that the path of the carrier is controlled independently.



Switching



#### a) Solid (form) braiding

Adapted maypole machines can be used to produce solid braids with square cross-section, known as gasket / 2.5D / packing / form braids. The carriers have a square arrangement according to the number of tracks to be formed by the braiders: 2-track system (2D braids, where D stands for diagonal); 3-track system (3D braids) and 4-track system (4D braids).

Graphite packing is a highly resistant sealant used in systems with valves, faucets, and stuffing boxes, as well as other machines with watertight mechanical parts. It can be applied either to static valve stems or to moving joints. Graphite packing offers high chemical resistance, great lubricity, and excellent thermal conductivity.





PTFE fluocarbon filament tape.

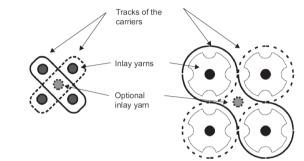
Use - Glass and glass-lined pipe flanges, Glass and glass-lined pipe vessels, Stainless steel reactors, Ceramic-lined tanks and vessels. Recommended for the most severe services. All oxidizers and corrosives with one exception: molten alkali metals. Temperature up to 260°C; pH range 0 - 14.

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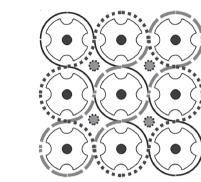


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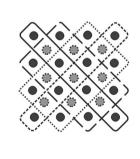


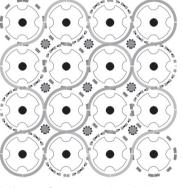
Two-track braiding of square braids



#### Three-track braiding of square braids

The packing braiding machine (Herzog) can be adapted for 2, 3 or 4-track. It presents sleeve type carriers, according to the pitch size for bobbin sizes of 72 x 285 mm up to 135 x 300 mm.





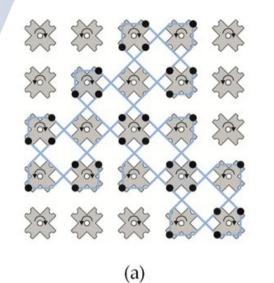
Four-track braiding of square braids





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(b)

(a) Programming of bobbin configuration; (b) 3D braided textile preform in a T-profile-like geometry.

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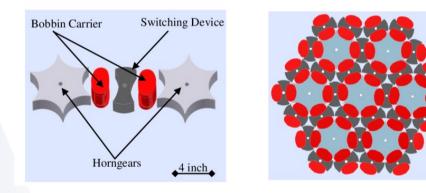


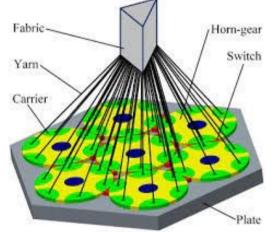
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#### b) Hexagonal braiding

Hexagonal 3D braiding is based on a different approach to horn gear 3D braiding by arranging the horn gears in a hexagonal shape. This position ensures the carriers are displaced with smaller increments, as they are closely to each other, thus changing the angle between braided yarns.



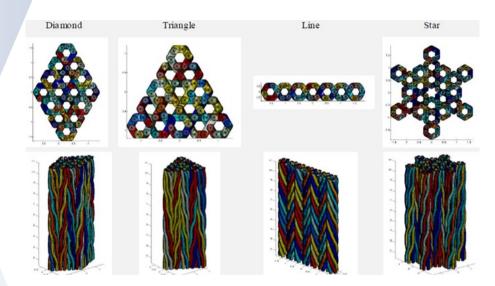


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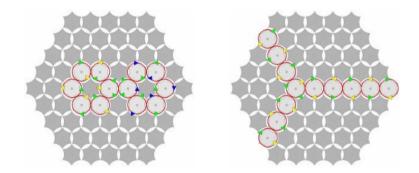


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Simulations of possible hexagonal braided structures and shapes



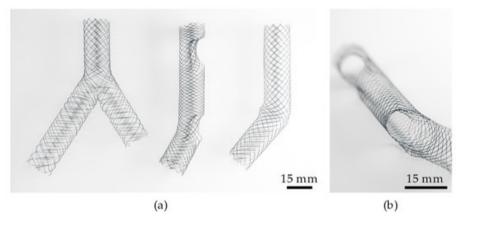
3D-braiding patterns: Double tubular (left) and Y-beam (right).



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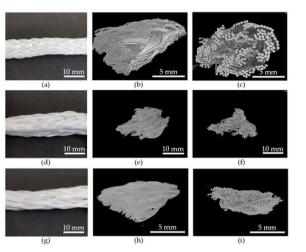


#### Applications of hexagonal braiding in medicine



Complex nitinol stent structures manufactured by 3D hexagonal braiding: (a) bifurcation stent, stent with patient individualized cut-outs, and J-stent with a diameter of 15 mm; (b) close-up of the cut-outs created by changing the braiding pattern from a round to a flat braid.

https://www.mdpi.com/2673-7248/1/2/9/htm



Different 3D braided scaffold designs manufactured on the 3D hexagonal braiding machine: (a-c) "multilayer braid", (d-f)"three-tube braid", (g-i) "six-tube braid"; (a,d,g) photographs, (b,c,e,f,h,i) microcomputed tomography (µ-CT) scans.

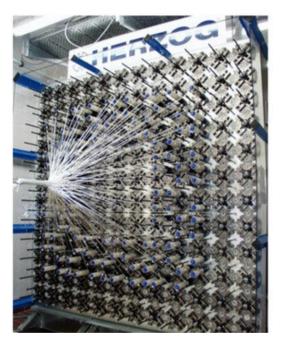
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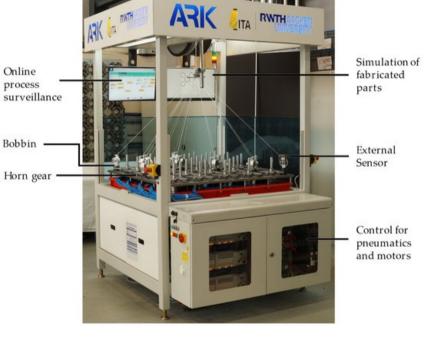
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#### **Rotary braiding Herzog**



9-module Herzog 3D rotary braiding machine



Retrofitted rotary 3D braiding machine at Institut für Textiltechnik (ITA)

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#### Rotary braiding 3TEX

The US company 3TEX designed a rotary braiding machine that presented an original track-switching mechanism where carriers are transferred between horn gears in pairs using a rotary gripping fork (called RGF). The horn gears are arranged in elementary cells that are assembled to form modules and these modules can be put together to create different configurations in terms of geometry and size. This composed architecture of the machine's arrangement and the CAD system developed to define the activation pattern of the RGFs according to shape allow for an enhanced production flexibility in terms of fabric geometry and cross-section.







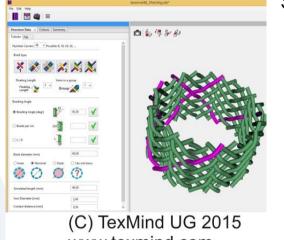
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### 3. CAD systems for modelling the braiding process

#### 3.1. TexMind software

**TexMind Braider** is an intuitive CAD-Software for colour and structural design of standard tubular and flat braids. The user defines the number of the yarns, the braiding type and the dimension of the braid. It has a Standard version and a Multifilament version.



www.texmind.com



Yarn Data			
Yarn Linear Density	tex	22.98	
Yarn Type	-Name-	PES	
Yarn Density	g/cm*3	1.3	
Yarn Diameter	mm	0.15	0.00591
Number Yams(plays) at one bobbin		6	
Effective Yarn Fineness (per Carrier	tex	137.88	
Bobbin Data			
Bobbin Min Diameter	cm	1.5	
Bobbin Max Diameter	cm	2.5	
Bobbin Width	cm	100	
Bobbin Volume	cm*3	314.15	
Wound Package Density	g/cm*3	0.8	
Bobbin Masse	9	251.32	
Bobbin Length	km	1.82	
Winding Machine Data			
Winding Velocity	m/min	1	
Total Winding Time per Bobbin	min	1822.74	
Number Winding Heads	-	1	
Total Winding Time for all carriers	min	43745.87	
Braid Data			
Rope Length (without knots)	km	1.82	
Rope Masse per meter	9	3.31	
Braiding Machine Data			
Meters Rope per Hour	m	200.40	
Hours to next bobbin Change	hour	5.10	
Braid coverage			
Angle ANSU/SCTE 51 2002	Deg		46.11
•			0.96
Cover Factor AMSU/SCTE 51 2002 C) TexMind UG 20	%		99.86

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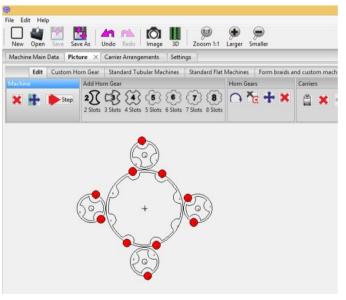


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**Texmind Braiding Machine Configurator** simulates the braiding process using horn gears with any number of slots, according to carrier placement. The software creates an animation of the carrier motion and checks for possible collision. It also simulates the idealized 3D structure of the braid.

- Horn gears with 2,3,4,5,6,7,8,....
- Any number of slots
- Carrier placement
- Show animation of the carrier motion
- Idealized 3D structure of the braid
- Collision check
- Export the machine drawing as WMF (windows 0 image format) and SVG (Corel Draw, Web)
- Export the braid as 3D geometry or jpg 0
- Export the machine emulation as GIF animation Ο

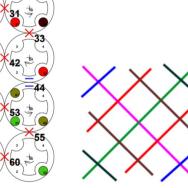


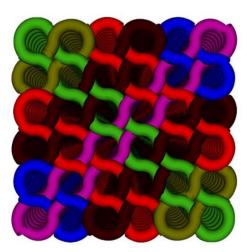


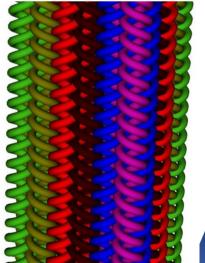
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Braiding machine configuration for production of solid braided structure with not full connected 10 tracks











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1 varn diamete

2 rope diamete

3 varn length/bobbin throug

4 yarn length/bobbin through diar

5 rope weigh

carrier varn titer through rone di

further programmes

#### 3.2. Herzog software

Computer Aided Braiding (CAB) by August Herzog Textilmaschinenfabric GmbH for their braiding machinery

Braid Description		Working on left picture	2				V V V
name of	product		0.3	00000			
Bu 4	0 22		4 1				XXX X
	-		•	00000			000
Kind of braid	Round-Braid						
Braiding	2 · 2						
occupation unber of carriers	40		• S				
under or camers	40		10				
			12		19 20		
noosing of colours			13		18		
			14		17		
			15	300000	15 16		XXX
			16				
oosing of definite		Colour	18		13 14		
-		hme	0 19		11 12		
red colour value		- Show colour values	20				
en colour value l		Please choose no. of carried			9 <sup>10</sup>		
lue colour value I			20 19		. 8	20 19	
		Anti-clockwise direction	18 17	22222	1	18	
		Carrier number: 1			56	18 17	<b>XXX</b>
Transfer choo	sen colour	red green blue	<sup>16</sup> 15	<b>~~~</b> ~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~	. 4	16 15	
					3	14	
educing scale		change braiding angle	<sup>14</sup> 13		1 2	1 13	XXX.
Choosing red	uced scale	choose braiding angle	12 11	<b>~~~</b>		12 11	<b>000</b>
	•	4 >	10 9			10 9	XXX
			8 .			8 . 3	
Width of Brain	d (mm) = 36	braiding angle (*)+50					X X X

2. CAB Design – simulation of braid structures, including colour patterns

4. MDA – Machine data acquisition

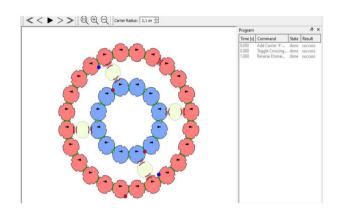
24/03/2022



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1. CAB Calculations – for braid design and machine operation



6 output calculation

7 approx machine dimensions

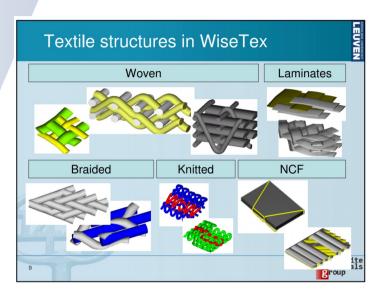
8 machine running time/bobbin set

9 braiding angle-/laylength calculatio 0 conversion of varn indications

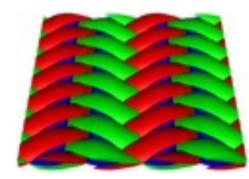
rope length per drum

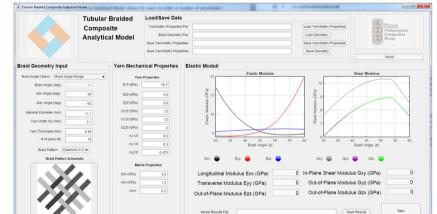
end programme

3. CAB Soft – simulation of carrier paths on advanced braiding machines



WiseTex 3.0 design of textile reinforced composites (KU Leuven, Belgium) TexGen - open source software developed for modelling the geometry of textile structures. (University of Nottingham)





# Braid CAM - design and manufacture of braided composites



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#### **The partners**



<u>Project Coordinator</u> UPC - Universitat Politècnica de Catalunya **Spain** 



ISMMM - Higher Institute of Fashion of Monastir Tunisia

ISET - Higher Institute of

Tunisia

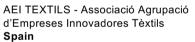


USF - University of Sfax Tunisia



CIAPE - Centro Italiano per l'Apprendimento Permanente Italy







CRE.THI.DEV - Creative Thinking Development Greece



CEDECS – TCBL – Consultancy for European Development of Ecological and Social entrepreneurship – Textile and Clothing Business Labs



KSAR-HELLAI

MFCPole - The Pôle de Compétitivité Monastir-El Fejja **Tunisia** 

Technological Studies of Ksar Hellal



CRNS - Centre de Recherche en Numérique de Sfax **Tunisia** 



ATCTex - Tunisian Association for Textile Researchers **Tunisia** 



UNIWA - University of West Attica Greece



TUIASI – Gehorghe Asachi University of Iași **Romania** 

24/03/2022



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